Disorder perturbation expansion for athermal crystals

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We introduce a perturbation expansion for athermal systems that allows an exact determination of displacement fields away from the crystalline state as a response to disorder. We show that the displacement fields in energy-minimized configurations of particles interacting through central potentials with microscopic disorder can be obtained as a series expansion in the strength of the disorder. We introduce a hierarchy of force-balance equations that allows an order-by-order determination of the displacement fields, with the solutions at lower orders providing sources for the higher-order solutions. This allows the simultaneous force-balance equations to be solved, within a hierarchical perturbation expansion to arbitrary accuracy. We present exact results for an isotropic defect introduced into the crystalline ground state at linear order and second order in our expansion. We show that the displacement fields produced by the defect display interesting self-similar properties at every order. We derive a $|\delta r| \sim 1/r$ and $|\delta f| \sim 1/r^2$ decay for the displacement fields and excess interparticle forces at large distances r away from the defect. Finally, we derive nonlinear corrections introduced by the interactions between defects at second order in our expansion. We verify our exact results with displacement fields obtained from energy-minimized configurations of soft disks.

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I. INTRODUCTION

Athermal materials represent a class of disordered systems where large-scale properties are only weakly affected by ambient thermal fluctuations. Such behavior emerges in many disordered systems when cooled to low temperatures [1]. These systems display arrested dynamics and can be described purely by their energy or enthalpy minimized states [2-5]. Being governed purely by local constraints of mechanical equilibrium, athermal systems display amorphous disorder that arises from the many possible arrangements of particles in minimum energy configurations. Such amorphous packings are inhomogeneous at the local scale and consequently are not described by the usual elasticity theories in continuum [6]. Since the thermal motion of the constituent particles is irrelevant, athermal materials are not governed by fluctuation dissipation relations [7], and therefore offer interesting arenas to study nonequilibrium behavior. Many real-world systems can be classified as athermal, and they arise frequently in physics and biology. Examples include jammed packings of particles [8-17], low temperature glasses [18,19], as well as densely packed tissues [20].

A fundamental type of disorder that arises in jammed athermal systems is polydispersity in particle sizes [11,21,22], which leads to amorphous energy-minimized structures. This variation in particle sizes give rise to sources of localized stress within the material and are usually referred to as stress defects [23,24]. Such defects play an important role in the bulk properties as well as the dynamics of amorphous systems. At the continuum scale stress defects have been modeled using bulk properties such as the elastic moduli of the medium and defect [25,26], however theories that incorporate microscopic disorder in the material are still missing. When the finite sizes of particles are considered, constructing coarse grained elasticity theories that account for disorder at the granular level becomes hard [27]. At the local scale, the nonlinearities involved in mechanical equilibrium conditions become important, as they have to be simultaneously satisfied by the entire configuration. This has made the characterization of athermal disorder and consequently the construction of statistical mechanical theories challenging [28–31].

Since the coupled nonlinear equations of force balance at the microscopic scale are challenging to solve, many properties of athermal materials are only accessible numerically through sophisticated minimization procedures. Theoretical studies of force-balanced networks have focused on diffusive models for scalar forces [32,33], as well as vectors along fixed lattice directions [29]. However, incorporating force balance with continuous vectors within a microscopic model has remained elusive. In this context, models of disordered athermal materials that can be exactly solved are important tools with which to understand athermal disorder as well as the sensitive deviations from linear elasticity that such materials display. A particularly appealing class of systems are disordered athermal crystals where the periodicity of a reference configuration can be exploited [22,34], and consequently they offer a paradigm where exact results for disordered athermal systems can be obtained.

In this paper we develop a systematic perturbation expansion [35,36] about the crystalline ordered state as a response to microscopic disorder for near-crystalline jammed systems.

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Such near-crystalline systems display glassy and jamming features although they are highly ordered [37-39]. We introduce a hierarchy of simultaneous equations arising from microscopic force balance at each site, which can be solved at each order in the expansion. This allows an exact determination of the displacement fields that develop as a response to the disorder. We illustrate our techniques with an application to a model of polydispersed soft disks, where quenched disorder is introduced into the particle sizes, parametrized by a polydispersity parameter. We illustrate the convergence properties of such an expansion by a detailed analysis of a single defect introduced into a crystalline background. We also theoretically predict the displacement fields produced by a single defect in such a crystalline arrangement up to second order. We find that these displacement fields display a remarkable self-similar behavior, with the solutions at higher orders in the perturbation theory resembling rescaled solutions at lower orders. To illustrate the nontrivial nature of the higher-order terms in the perturbation expansion, we provide experimentally testable predictions arising from second-order corrections, that are not captured by continuum elasticity theories.

The plan of this paper is as follows. In Sec. III we develop a hierarchical perturbation expansion about the crystalline state, that allows us to exactly solve the equations of force balance and obtain the displacement fields to arbitrary accuracy. In Sec. IV we examine the displacement fields generated by our expansion at linear order. We also examine the higher-order solutions, providing exact equations up to second order. In Sec. V we contextualize our results in a model crystal composed of deformable disks, interacting through a paradigmatic soft-sphere Hamiltonian. Next, we examine the displacement fields produced by introducing a single defect into this system in Sec. VI. We derive exact results for these displacement fields at second order. We also examine the excess forces produced by this defect in Sec. VII. In Sec. VIII we derive the large length-scale behavior of the displacement and excess force fields produced by the single defect. We also discuss the universal features of our results, and their relation to continuum elasticity. Finally, in Sec. IX, we study the nature of the nonlinear interactions between particles generated in our perturbation expansion, through the study of the displacement fields created by two defects in the crystalline system. We also provide an experimentally testable prediction which can be used to extract such nonlinear interactions in athermal crystals. Finally, we conclude in Sec. X and provide avenues for further research.

II. ATHERMAL CRYSTALS

The ground state of a system of particles interacting through short ranged central potentials is a triangular lattice arrangement [40]. The introduction of disorder can lead to fluctuations in the positions, and consequently elastic properties such as the local shear modulus [41,42]. Many studies have considered the effect of small disorder about the crystalline state, whose periodicity facilitates an exact theoretical treatment of their properties. However, when disorder is introduced into an athermal system, such as in amorphous configurations, developing theories that predict macroscopic properties becomes challenging [39,43,44]. In such crystals,



FIG. 1. The lattice convention used in this paper. We place the sites of the triangular lattice on a $2L \times L$ rectangular grid, with the triangular lattice sites *i* at position $\vec{r}_i \equiv (X, Y)$ such that mod(X + Y, 2) = 0. The lattice sites (particles) are represented by filled blue circles, and the lattice constant in the crystalline arrangement is R_0 . Each particle *i* has six neighbors which are labeled j = 0 to 5. The bond angles between these particles *i* and *j* with respect to the *x* axis are given by, $\theta_{ij}^0 = \frac{2\pi j}{6}$. As a response to the disorder, the particles are displaced to new locations (green circles). Here δx and δy represent the displacement of the particles from their original positions along the *x* and *y* directions, respectively. The directions parallel (\hat{r}_{\parallel}) and orthogonal (\hat{r}_{\perp}) to the lattice directions are represented with blue arrows.

the contribution of lattice phonons is suppressed, and crystallization results from energy minimization, and they exhibit properties of *athermal* materials. Many examples of such disordered near-crystalline systems exist including glasses with high crystalline order [45–47], polycrystals [48,49], as well as colloidal crystals [50]. In such systems, the changes in the interparticle potentials introduced through quenched disorder affects their large-scale properties when force-balance conditions are exactly imposed, leading to amorphous structures. This leads to elastic heterogeneity at the microscopic scale, and therefore continuum elasticity frameworks are inapplicable in such materials.

In this work we consider *prestressed* crystals [22], where finite forces exist between the particles in the crystalline state. This is accomplished by the boundary conditions that confine the system. Examples include Wigner crystals, where particles interacting through central potentials crystallize under confinement at high densities [51] and jammed soft particle packings [21,39]. We model such systems by considering a triangular lattice of particles with a lattice constant R_0 (see Fig. 1). For ease of computation we place the sites of the triangular lattice on a $2L \times L$ rectangular grid with the lattice sites $\vec{r}_i \equiv (X, Y)$ by maintaining mod(X + Y, 2) = 0 [52] as shown in Fig. 1. Although, we use this convention in our computations, all the plotted figures represent our results on the actual triangular lattice. Thus the reciprocal lattice vector can be written as

$$\vec{k} \equiv (k_x, k_y) \equiv \left(\frac{2\pi l}{2L}, \frac{2\pi m}{L}\right),\tag{1}$$

and the volume of the system is $V = 2L^2$. We also define fundamental lattice translation vectors $\vec{\mathbf{r}}_0 = (2, 0)$, $\vec{\mathbf{r}}_1 = (1, 1)$, $\vec{\mathbf{r}}_2 = (-1, 1)$, $\vec{\mathbf{r}}_3 = (-2, 0)$, $\vec{\mathbf{r}}_4 = (-1, -1)$, $\vec{\mathbf{r}}_5 = (1, -1)$.

III. DISORDER PERTURBATION EXPANSION

We begin by analyzing the response of the crystalline state to the presence of small amounts of disorder. The energyminimized configuration with no disorder in the microscopic potential is the triangular lattice arrangement of particles (see Fig. 1). Our formulation considers any central force law with microscopic disorder, that causes a perturbation of the system away from the crystalline state. We consider particles interacting through pairwise central potentials of the form

$$u(\vec{r}_{ij}, \{\zeta_i\}) = \mathcal{F}(|\vec{r}_{ij}|, \{\zeta_i\}).$$
(2)

Here $\vec{r}_{ij} = \vec{r}_j - \vec{r}_i$ is the vector distance between the particles *i* and *j* located at positions \vec{r}_i and \vec{r}_j , respectively. In this paper, we focus our discussion considering the pairwise central potential is short ranged. The variables { ζ_i } represent quenched scalar variables at every site, which can be tuned to create pertubations about the crystalline state. Additionally we assume that the bond energy $u(\vec{r}_{ij}, \{\zeta_i\})$ associated with pairs of particles *i* and *j*, is symmetric with respect to the scalar disorder at each site, i.e., it is a function of $\delta\zeta_i + \delta\zeta_j$. In Secs. V–VIII we describe an application of our theory for such a potential, a system of polydispersed soft disks where the quenched variable { ζ_i } is identified with the radii of the particles. The total energy is represented as a sum over all interacting pairs of particles, which can be expressed as a sum of their bond energies,

$$U(\{\zeta_i\}) = \frac{1}{2} \sum_{ij} u(\vec{r}_{ij}, \{\zeta_i\}).$$
(3)

Next, Eq. (2) can be used to derive the interparticle forces as

$$\vec{f}_{ij}(\vec{r}_{ij}) = -\partial_{|\vec{r}_{ii}|} \mathcal{F}(|\vec{r}_{ij}|, \{\zeta_i\}) \hat{r}_{ij}, \tag{4}$$

where \hat{r}_{ij} is the unit vector along the interparticle distance vector. We can decompose the forces along the *x* and *y* directions as $\vec{f} = (f^x, f^y)$. Crucially for central potentials the vector \vec{f}_{ij} reverses sign under index interchange $i \leftrightarrow j$.

We focus specifically on states in mechanical equilibrium, i.e., energy-minimized configurations. Our formulation applies for attractive as well as repulsive potentials. Each configuration of the disordered system has contact forces $\{\vec{f}_{ij}\}\$ between particles *i* and *j*. The ground states of the system consist of configurations with each particle in force balance. We have

$$\sum_{j} f_{ij}^{x} = 0, \quad \sum_{j} f_{ij}^{y} = 0, \quad \forall i.$$
 (5)

Here $f_{ij}^{x(y)}$ are the x(y) components of the forces between particles *i* and *j*, and the sum is over all particles *j* in contact with particle *i*. In the next section we use the perturbed solutions described above to solve these force-balance equations at each order. The perturbation away from the crystal can be parametrized by the scalar variable at each site as

$$\zeta_i = \zeta_0 + \lambda \delta \zeta_i. \tag{6}$$

Here, the variable λ represents a tuning parameter that controls the strength of the quenched disorder in the system, $\lambda = 0$ corresponds to the crystalline state.

As a response to the presence of disorder, the positions of the particles deviate from their crystalline values $\vec{r}_i^{(0)} = \{x_i^{(0)}, y_i^{(0)}\}$ to a new mechanical equilibrium configuration $\vec{r}_i = \{x_i, y_i\}$. We define the vector *displacement field* $\{\delta \vec{r}_i\}$ from the crystalline state at every site *i* as

$$\vec{r}_i = \vec{r}_i^{(0)} + \delta \vec{r}_i. \tag{7}$$

A crucial aspect of our analysis is the decomposition of the displacement fields into their components along the fixed coordinate directions x, y, ... as $\{\delta \vec{r}_i\} \equiv \{\delta x_i, \delta y_i, ...\}$. This allows us to exactly determine the displacements in the presence of disorder. This can be accomplished since the perturbed positions can be used to generate the excess forces through the microscopic force law in Eq. (4). In *d* dimensions, the *Nd* component displacement field vector can then be uniquely determined by the *Nd* equations of force balance in the system. In this paper, we present results focused on two dimensional systems (d = 2), however our techniques can be extended to higher dimensional systems as well. The perturbed positions at each site *i* can be expressed as

$$x_i = x_i^{(0)} + \delta x_i,$$

$$y_i = y_i^{(0)} + \delta y_i.$$
(8)

The forces $\vec{f}_{ij} = (f_{ij}^x, f_{ij}^y)$ between any two particles *i* and *j* also change in response to this perturbation in the positions. We have

$$f_{ij}^{x} = f_{ij}^{x(0)} + \delta f_{ij}^{x},$$

$$f_{ij}^{y} = f_{ij}^{y(0)} + \delta f_{ij}^{y},$$
(9)

where $\{f_{ij}^{x(0)}, f_{ij}^{y(0)}\}\$ are the forces along the *x* and *y* directions between particles *i* and *j* in the crystalline ordered state. It is also convenient to define relative displacements between two neighboring particles,

$$\delta x_{ij} = \delta x_j - \delta x_i, \tag{10}$$

$$\delta y_{ij} = \delta y_j - \delta y_i,$$

as well as a corresponding sum involving the quenched random variables at neighboring particles,

$$\delta\zeta_{ij} = \delta\zeta_j + \delta\zeta_i. \tag{11}$$

Our analysis begins with the expansion of the interparticle forces in terms of the perturbed positions. In previous work, the linear-order solutions of the displacement fields was derived, for disorder introduced into the particle sizes [22,34]. Here, we provide a generalized version of the theory for different types of disorder and underlying interparticle potentials. We also extend the framework to include higher-order terms in the perturbation expansion. The force \vec{f}_{ij} between particles *i* and *j* can be Taylor expanded about its value in the crystalline

ground state as

$$\delta f_{ij}^{x} = C_{ij}^{xx} \delta x_{ij} + C_{ij}^{xy} \delta y_{ij} + C_{ij}^{x\zeta} \delta \zeta_{ij} + C_{ij}^{xxx} \delta x_{ij} \delta x_{ij} + C_{ij}^{xxy} \delta x_{ij} \delta y_{ij} + C_{ij}^{xyy} \delta y_{ij} \delta y_{ij} + C_{ij}^{xx\zeta} \delta x_{ij} \delta \zeta_{ij} + C_{ij}^{xy\zeta} \delta y_{ij} \delta \zeta_{ij} + C_{ij}^{x\zeta\zeta} \delta \zeta_{ij} \delta \zeta_{ij} + \dots \delta f_{ij}^{y} = C_{ij}^{yx} \delta x_{ij} + C_{ij}^{yy} \delta y_{ij} + C_{ij}^{y\zeta} \delta \zeta_{ij} + C_{ij}^{yxx} \delta x_{ij} \delta x_{ij} + C_{ij}^{yxy} \delta x_{ij} \delta y_{ij} + C_{ij}^{yyy} \delta y_{ij} \delta y_{ij} + C_{ij}^{yx\zeta} \delta x_{ij} \delta \zeta_{ij} + C_{ij}^{yy\zeta} \delta y_{ij} \delta \zeta_{ij} + C_{ij}^{y\zeta\zeta} \delta \zeta_{ij} \delta \zeta_{ij} + \dots$$
(12)

The coefficients $C_{ij}^{\alpha\beta}$ and $C_{ij}^{\alpha\beta\gamma}$ do not depend on the particle index *i*, as they are translationally invariant, being expressible purely in terms of the reference crystalline state. The general coefficient in the expansion at first order is given by

$$C_{ij}^{\alpha\beta} = -\frac{\partial \left[\mathcal{F}\left(\frac{r_{ij}^{\alpha}}{r_{ij}}\right)\right]}{\partial r^{\beta}}\bigg|_{r_{ij}^{\beta(0)}},$$
(13)

where $\beta \equiv x, y, ..., \zeta$ accounts for the spatial as well as disorder indices and $r_{ij}^{\beta(0)}$ represents the bond variables between particles *i* and *j* with $r_{ij}^x \equiv x_{ij} = x_j - x_i, r_{ij}^y \equiv y_{ij} = y_j - y_i$, ..., and $r_{ij}^{\zeta} \equiv \zeta_{ij} = \zeta_j + \zeta_i$. Similarly, $r_{ij}^{\beta(0)}$ represents the values of these quantities in the crystalline state. We note that the coefficients relating only to the spatial components C_{ij}^{xx}, C_{ij}^{xy} ... are equivalent to the elements of the Hessian matrix of the system [53]. Next, the general coefficient at second order is given by

$$C_{ij}^{\alpha\beta\gamma} = -\frac{\partial^2 \left[\mathcal{F}\left(\frac{r_{ij}^{\mu}}{r_{ij}}\right) \right]}{\partial r_{ij}^{\beta} \partial r_{ij}^{\gamma}} \bigg|_{r_{ij}^{\beta(0)}, r_{ij}^{\gamma(0)}}.$$
 (14)

Here $r_{ij} = \sqrt{\sum_{\alpha} r_{ij}^{\alpha} r_{ij}^{\alpha}}$ represents the magnitude of the distance vector \vec{r}_{ij} . The higher-order coefficients can be obtained in a similar manner. The interparticle forces, being drawn from the central potential have the form $f_{ij}^{x(y)} = \kappa (x_{ij}, y_{ij}, \zeta_{ij}) \frac{x(y)_{ij}}{r_{ij}}$, which is antisymmetric upon exchange of index $i \leftrightarrow j$. Therefore, the terms at every order in the above force expansion should be antisymmetric with respect to this index interchange. Since $\delta x(y)_{ij}$ is antisymmetric, the *n*th order coefficients $C_{ij}^{\alpha\beta\gamma\dots}$ is antisymmetric if the combined factors of δx , δy , and $\delta \zeta$ associated with the coefficient are symmetric and vice versa.

Next, we expand the perturbed positions away from the crystalline state as an expansion in the disorder tuning parameter λ as

$$x_{i} = x_{i}^{(0)} + \lambda \delta x_{i}^{(1)} + \lambda^{2} \delta x_{i}^{(2)} + \lambda^{3} \delta x_{i}^{(3)} + \dots$$

$$y_{i} = y_{i}^{(0)} + \lambda \delta y_{i}^{(1)} + \lambda^{2} \delta y_{i}^{(2)} + \lambda^{3} \delta y_{i}^{(3)} + \dots$$
(15)

Here $\{\delta x_i^{(n)}, \delta y_i^{(n)}\}$ represent the *n*th order displacement fields, which are of magnitude $\mathcal{O}(\lambda^n)$. We also define the relative

displacements at every order:

$$\delta x_{ij}^{(1)} = \delta x_j^{(1)} - \delta x_i^{(1)},$$

$$\delta y_{ij}^{(1)} = \delta y_j^{(1)} - \delta y_i^{(1)},$$

$$\delta x_{ij}^{(2)} = \delta x_j^{(2)} - \delta x_i^{(2)},$$

$$\delta y_{ij}^{(2)} = \delta y_j^{(2)} - \delta y_i^{(2)},$$

$$\vdots \qquad (16)$$

Similarly, the change in forces in Eq. (4) can also be expressed as an expansion in the parameter λ , given by

$$\delta f_{ij}^{x} = \lambda \delta f_{ij}^{x(1)} + \lambda^{2} \delta f_{ij}^{x(2)} + \lambda^{3} \delta f_{ij}^{x(3)} + \mathcal{O}(\lambda^{4}),$$

$$\delta f_{ij}^{y} = \lambda \delta f_{ij}^{y(1)} + \lambda^{2} \delta f_{ij}^{y(2)} + \lambda^{3} \delta f_{ij}^{y(3)} + \mathcal{O}(\lambda^{4}). \quad (17)$$

Inserting the expressions in Eqs. (15) and (16) into Eq. (17), and matching terms at first order, we obtain the change in interparticle forces at linear order along the *x* and the *y* directions. We have

$$\delta f_{ij}^{x(1)} = C_{ij}^{xx} \delta x_{ij}^{(1)} + C_{ij}^{xy} \delta y_{ij}^{(1)} + C_{ij}^{x\zeta} \delta \zeta_{ij},$$

$$\delta f_{ij}^{y(1)} = C_{ij}^{yx} \delta x_{ij}^{(1)} + C_{ij}^{yy} \delta y_{ij}^{(1)} + C_{ij}^{y\zeta} \delta \zeta_{ij}.$$
 (18)

Similarly, matching terms at second order in Eq. (17), we arrive at the second-order change in forces

$$\begin{split} \delta f_{ij}^{x(2)} &= C_{ij}^{xx} \delta x_{ij}^{(2)} + C_{ij}^{xy} \delta y_{ij}^{(2)} + C_{ij}^{xxx} \delta x_{ij}^{(1)} \delta x_{ij}^{(1)} \\ &+ C_{ij}^{xxy} \delta x_{ij}^{(1)} \delta y_{ij}^{(1)} + C_{ij}^{xyy} \delta y_{ij}^{(1)} \delta y_{ij}^{(1)} + C_{ij}^{xx\zeta} \delta x_{ij}^{(1)} \delta \zeta_{ij} \\ &+ C_{ij}^{xy\zeta} \delta y_{ij}^{(1)} \delta \zeta_{ij} + C_{ij}^{x\zeta\zeta} \delta \zeta_{ij} \delta \zeta_{ij}, \\ \delta f_{ij}^{y(2)} &= C_{ij}^{yx} \delta x_{ij}^{(2)} + C_{ij}^{yy} \delta y_{ij}^{(2)} + C_{ij}^{yxx} \delta x_{ij}^{(1)} \delta x_{ij}^{(1)} \\ &+ C_{ij}^{yxy\delta} \delta x_{ij}^{(1)} \delta y_{ij}^{(1)} + C_{ij}^{yyy\delta} \delta y_{ij}^{(1)} \delta y_{ij}^{(1)} + C_{ij}^{yx\zeta\delta} \delta x_{ij}^{(1)} \delta \zeta_{ij} \\ &+ C_{ij}^{yy\zeta\delta} \delta y_{ij}^{(1)} \delta \zeta_{ij} + C_{ij}^{y\zeta\zeta\delta} \delta \zeta_{ij} \delta \zeta_{ij}, \end{split}$$
(19)

The higher-order terms in this perturbation expansion can be obtained in a systematic manner as described above, with the coefficients depending only on the higher-order derivatives of the force law at R_0 , interparticle separation in the reference crystalline state.

IV. HIERARCHICAL FORCE BALANCE

In this section we use the perturbation expansion of the positions and forces developed above to derive the displacements of the particle positions away from the crystalline ordered state. This is accomplished by imposing the simultaneous force-balance conditions in Eq. (5) at every order. This provides enough equations to determine the displacement fields at each order. We show below that the displacement fields at every order can be determined uniquely within a hierarchical scheme, in which the solutions at lower orders act as "sources" that generate the displacement fields at higher orders.

A. Linear order

We begin by imposing the force-balance conditions at first order in our expansion. Considering only terms up to linear order in Eq. (5), we arrive at the following set of equations representing force balance along the x and y directions, respectively,

$$\sum_{j} \left(C_{ij}^{xx} \delta x_{ij}^{(1)} + C_{ij}^{xy} \delta y_{ij}^{(1)} + C_{ij}^{x\zeta} \delta \zeta_{ij} \right) = 0, \ \forall \ i,$$

$$\sum_{j} \left(C_{ij}^{yx} \delta x_{ij}^{(1)} + C_{ij}^{yy} \delta y_{ij}^{(1)} + C_{ij}^{y\zeta} \delta \zeta_{ij} \right) = 0, \ \forall \ i, \qquad (20)$$

where the coefficients $C_{ij}^{\beta\gamma}$ depend only on the lattice constant R_0 and the neighbor *j*. For a system of *N* particles, there are 2*N* force-balance constraints at every order. To calculate the displacement field for the entire system at a given order, one needs to solve these 2*N* equations simultaneously, which requires the inversion of a $2N \times 2N$ matrix. This is challenging for a system with a large number of particles. However, as the coefficients $C_{ij}^{\alpha\beta}$ are translationally invariant, a Fourier transform of the above equations helps to block diagonalize this matrix, into 2×2 blocks corresponding to each reciprocal lattice point \vec{k} . The Fourier transforms of the changes in positions and radii can be defined as

$$\delta \tilde{x}^{(1)}(\vec{k}) = \sum_{\vec{r}} \exp(i\vec{k}.\vec{r})\delta x^{(1)}(\vec{r}),$$

$$\delta \tilde{y}^{(1)}(\vec{k}) = \sum_{\vec{r}} \exp(i\vec{k}.\vec{r})\delta y^{(1)}(\vec{r}),$$

$$\delta \tilde{\zeta}(\vec{k}) = \sum_{\vec{r}} \exp(i\vec{k}.\vec{r})\delta \zeta(\vec{r}).$$
(21)

Here \vec{r} labels the sites of the triangular lattice whereas \vec{k} are the reciprocal lattice vectors defined in Eq. (1). We note that the discrete Fourier transform defined above involves the original crystalline positions $\vec{r} \equiv \vec{r}_i^{(0)}$, which we use interchangeably as the site index $\vec{r} \equiv i$. It is also convenient to define the basic translation coefficients in Fourier space (using the notation in Fig. 1)

$$\mathcal{F}_j(\vec{k}) = \exp(-i\vec{k}.\vec{r}_j),\tag{22}$$

where \vec{r}_j are the fundamental lattice translation vectors. Next, multiplying Eq. (20) by $\exp(i\vec{k}.\vec{r})$ and summing over all sites $\vec{r} \equiv i$ leads to the following matrix equation at every reciprocal lattice point \vec{k} :

$$\begin{bmatrix} A^{xx}(\vec{k}) & A^{xy}(\vec{k}) \\ A^{yx}(\vec{k}) & A^{yy}(\vec{k}) \end{bmatrix} \begin{bmatrix} \delta \tilde{x}^{(1)}(\vec{k}) \\ \delta \tilde{y}^{(1)}(\vec{k}) \end{bmatrix} = -\delta \tilde{\zeta}(\vec{k}) \begin{bmatrix} D^{x}(\vec{k}) \\ D^{y}(\vec{k}) \end{bmatrix}.$$
(23)

We can interpret the matrix A as an inverse Green's function of the system in Fourier space. The matrix elements of the inverse Green's function have the following explicit representations:

$$A^{xx}(\vec{k}) = -\sum_{j=0}^{5} [1 - \mathcal{F}_j(\vec{k})] C_{ij}^{xx},$$
$$A^{xy}(\vec{k}) = -\sum_{j=0}^{5} [1 - \mathcal{F}_j(\vec{k})] C_{ij}^{xy},$$

$$A^{yx}(\vec{k}) = -\sum_{j=0}^{5} [1 - \mathcal{F}_j(\vec{k})] C_{ij}^{yx},$$

$$A^{yy}(\vec{k}) = -\sum_{j=0}^{5} [1 - \mathcal{F}_j(\vec{k})] C_{ij}^{yy}.$$
 (24)

Similarly we have

$$D^{x}(\vec{k}) = -\sum_{j=0}^{5} [1 + \mathcal{F}_{j}(\vec{k})] C_{ij}^{x\sigma},$$

$$D^{y}(\vec{k}) = -\sum_{j=0}^{5} [1 + \mathcal{F}_{j}(\vec{k})] C_{ij}^{y\sigma}.$$
 (25)

B. Response Green's functions

The Green's function can be expressed as a matrix:

$$\tilde{G} = A^{-1} = \begin{bmatrix} \tilde{G}^{xx}(\vec{k}) & \tilde{G}^{xy}(\vec{k}) \\ \tilde{G}^{yx}(\vec{k}) & \tilde{G}^{yy}(\vec{k}) \end{bmatrix}.$$
(26)

The elements $\tilde{G}^{\mu\nu}$ can in turn be expressed in terms of the coefficients $A^{\mu\nu}$, which depend on the underlying potential through the coefficients $C^{\alpha\beta}_{ij}$. We next define source terms in Fourier space as

$$\tilde{S}^{x(1)}(\vec{k}) = -D^{x}(\vec{k})\delta\tilde{\zeta}(\vec{k}),$$

$$\tilde{S}^{y(1)}(\vec{k}) = -D^{y}(\vec{k})\delta\tilde{\zeta}(\vec{k}).$$
(27)

Inverting Eq. (23), and using the above source, leads to an expression for the Fourier transformed displacement fields at first order in terms of the Fourier transform of the quenched disorder $\{\delta \tilde{\zeta}(\vec{k})\}$. We have

$$\delta \tilde{x}^{(1)}(\vec{k}) = [\tilde{G}^{xx}(\vec{k})\tilde{S}^{x(1)}(\vec{k}) + \tilde{G}^{xy}(\vec{k})\tilde{S}^{y(1)}(\vec{k})],$$

$$\delta y^{(1)}(\vec{k}) = [\tilde{G}^{yx}(\vec{k})\tilde{S}^{x(1)}(\vec{k}) + \tilde{G}^{yy}(\vec{k})\tilde{S}^{y(1)}(\vec{k})].$$
(28)

The displacement fields at linear order can then be computed as an inverse Fourier transform, yielding

$$\delta x^{(1)}(\vec{r}) = \sum_{\vec{r}'} G^{xx}(\vec{r} - \vec{r}') S^{x(1)}(\vec{r}') + \sum_{\vec{r}'} G^{xy}(\vec{r} - \vec{r}') S^{y(1)}(\vec{r}'),$$

$$\delta y^{(1)}(\vec{r}) = \sum_{\vec{r}'} G^{yx}(\vec{r} - \vec{r}') S^{x(1)}(\vec{r}') + \sum_{\vec{r}'} G^{yy}(\vec{r} - \vec{r}') S^{y(1)}(\vec{r}').$$
(29)

The real space Green's functions in the above expression are easily computed as an inverse transform of the Fourier space expressions in Eq. (26) as

$$G^{\mu\nu}(\vec{r}) = \frac{1}{V} \sum_{\vec{k}} e^{-i\vec{k}.\vec{r}} \tilde{G}^{\mu\nu}(\vec{k}).$$
(30)

In Sec. VIII we show that in the small k limit, $\tilde{G}^{\mu\nu}(\vec{k}) \sim 1/|k|^2$, implying a $G^{\mu\nu}(\vec{r}) \sim \log(|r|)$ behavior at large distances \vec{r} . These Green's functions in real space have been plotted in Fig. 2. The functions $G^{xy}(\vec{r}) = G^{yx}(\vec{r})$ display a quadrupolar structure at large distances, as opposed to the sixfold symmetry of the underlying triangular lattice.



FIG. 2. The Green's functions of the response $G^{\mu\nu}(\vec{r})$ in real space. (a) $G^{xx}(\vec{r})$, (b) $G^{xy}(\vec{r})$, (c) $G^{yx}(\vec{r})$, (d) $G^{yy}(\vec{r})$. The transverse Green's functions (G^{xy} and G^{yx}) have different limits in the $r \to \infty$ limit along different directions. All the Green's functions display a $\sim \log(|r|)$ dependence in the $r \to \infty$ limit. These Green's functions provide the solution to the displacement fields at all orders, with modified sources at each order. The behavior of these functions generates the long distance behavior of $\delta x(y)(\vec{r}) \sim \frac{1}{r}$ of the displacement fields away from a stress defect, for general pairwise potentials.

C. Second order

Similarly, we can impose the force-balance conditions at second order in our expansion, and extract the displacement fields as a solution of the corresponding simultaneous equations. Considering only terms at second order in Eq. (5), we arrive at the second-order force-balance equations along the x and y directions, respectively,

$$\sum_{j} \left(C_{ij}^{xx} \delta x_{ij}^{(2)} + C_{ij}^{xy} \delta y_{ij}^{(2)} + C_{ij}^{xxx} \delta x_{ij}^{(1)} \delta x_{ij}^{(1)} \right. \\ \left. + C_{ij}^{xxy} \delta x_{ij}^{(1)} \delta y_{ij}^{(1)} + C_{ij}^{xyy} \delta y_{ij}^{(1)} \delta y_{ij}^{(1)} + C_{ij}^{xx\zeta} \delta x_{ij}^{(1)} \delta \zeta_{ij} \right. \\ \left. + C_{ij}^{xy\zeta} \delta y_{ij}^{(1)} \delta \zeta_{ij} + C_{ij}^{x\zeta\zeta} \delta \zeta_{ij} \delta \zeta_{ij} \right) \\ = 0, \quad \forall i,$$

$$\sum_{j} \left(C_{ij}^{yx} \delta x_{ij}^{(2)} + C_{ij}^{yy} \delta y_{ij}^{(2)} + C_{ij}^{yxx} \delta x_{ij}^{(1)} \delta x_{ij}^{(1)} \right. \\ \left. + C_{ij}^{yxy} \delta x_{ij}^{(1)} \delta y_{ij}^{(1)} + C_{ij}^{yyy} \delta y_{ij}^{(1)} \delta y_{ij}^{(1)} + C_{ij}^{yx\zeta} \delta x_{ij}^{(1)} \delta \zeta_{ij} \right. \\ \left. + C_{ij}^{yy\zeta} \delta y_{ij}^{(1)} \delta \zeta_{ij} + C_{ij}^{y\zeta\zeta} \delta \zeta_{ij} \delta \zeta_{ij} \right) \\ = 0, \quad \forall i.$$

Once again at second order we have 2N simultaneous equations to solve. From Eq. (31), it is clear that the first-order solutions serve as the source for the second-order fields. These source terms in real space can be expressed as (with

$$\vec{r} \equiv i)$$

$$S_{i}^{x(2)} = \sum_{j} \left(C_{ij}^{xxx} \delta x_{ij}^{(1)} \delta x_{ij}^{(1)} + C_{ij}^{xxy} \delta x_{ij}^{(1)} \delta y_{ij}^{(1)} + C_{ij}^{xyy} \delta y_{ij}^{(1)} \delta y_{ij}^{(1)} \right)$$

$$+ C_{ij}^{xx\zeta} \delta x_{ij}^{(1)} \delta \zeta_{ij} + C_{ij}^{xy\zeta} \delta y_{ij}^{(1)} \delta \zeta_{ij} + C_{ij}^{x\zeta\zeta} \delta \zeta_{ij} \delta \zeta_{ij} \right),$$

$$S_{i}^{y(2)} = \sum_{j} \left(C_{ij}^{yxx} \delta x_{ij}^{(1)} \delta x_{ij}^{(1)} + C_{ij}^{yxy} \delta x_{ij}^{(1)} \delta y_{ij}^{(1)} + C_{ij}^{yyy} \delta y_{ij}^{(1)} \delta y_{ij}^{(1)} \right)$$

$$+ C_{ij}^{yx\zeta} \delta x_{ij}^{(1)} \delta \zeta_{ij} + C_{ij}^{yy\zeta} \delta y_{ij}^{(1)} \delta \zeta_{ij} + C_{ij}^{y\zeta\zeta} \delta \zeta_{ij} \delta \zeta_{ij} \right). (31)$$

The Fourier transforms of the second-order source terms can be defined as

$$\tilde{S}^{x(2)}(\vec{k}) = \sum_{\vec{r}} \exp(i\vec{k}.\vec{r})S^{x(2)}(\vec{r}),$$

$$\tilde{S}^{y(2)}(\vec{k}) = \sum_{\vec{r}} \exp(i\vec{k}.\vec{r})S^{y(2)}(\vec{r}).$$
 (32)

Using the above expressions, and following the same procedure as for linear order, we arrive at the following force balance equations in Fourier space at second order:

$$\begin{bmatrix} A^{xx}(\vec{k}) & A^{xy}(\vec{k}) \\ A^{xy}(\vec{k}) & A^{yy}(\vec{k}) \end{bmatrix} \begin{bmatrix} \delta \tilde{x}^{(2)}(\vec{k}) \\ \delta \tilde{y}^{(2)}(\vec{k}) \end{bmatrix} = \begin{bmatrix} \tilde{S}^{x(2)}(\vec{k}) \\ \tilde{S}^{y(2)}(\vec{k}) \end{bmatrix}.$$
 (33)

We note that the matrix A in the above equation is the same matrix that appears at first order in Eq. (23). Next, we can invert Eq. (33) and express the displacement fields using the Green's functions as

$$\begin{bmatrix} \delta \tilde{x}^{(2)}(\vec{k}) \\ \delta \tilde{y}^{(2)}(\vec{k}) \end{bmatrix} = \begin{bmatrix} \tilde{G}^{xx}(\vec{k}) & \tilde{G}^{xy}(\vec{k}) \\ \tilde{G}^{xy}(\vec{k}) & \tilde{G}^{yy}(\vec{k}) \end{bmatrix} \begin{bmatrix} \tilde{S}^{x(2)}(\vec{k}) \\ \tilde{S}^{y(2)}(\vec{k}) \end{bmatrix}.$$
(34)

The second-order displacement fields in Fourier space can then be written as

$$\begin{split} \delta \tilde{x}^{(2)}(\vec{k}) &= [\tilde{G}^{xx}(\vec{k})\tilde{S}^{x(2)}(\vec{k}) + \tilde{G}^{xy}(\vec{k})\tilde{S}^{y(2)}(\vec{k})],\\ \delta \tilde{y}^{(2)}(\vec{k}) &= [\tilde{G}^{yx}(\vec{k})\tilde{S}^{x(2)}(\vec{k}) + \tilde{G}^{yy}(\vec{k})\tilde{S}^{x(2)}(\vec{k})]. \end{split}$$
(35)

We therefore arrive at the following expressions for the displacement fields at second order

$$\delta x^{(2)}(\vec{r}) = \sum_{\vec{r}'} [G^{xx}(\vec{r} - \vec{r}')S^{x(2)}(\vec{r}') + G^{xy}(\vec{r} - \vec{r}')S^{y(2)}(\vec{r}')],$$

$$\delta y^{(2)}(\vec{r}) = \sum_{\vec{r}'} [G^{yx}(\vec{r} - \vec{r}')S^{x(2)}(\vec{r}') + G^{yy}(\vec{r} - \vec{r}')S^{y(2)}(\vec{r}')].$$
(36)

The Green's functions that appear above are the same as the Green's functions in the linear-order solution in Eq. (29). However, unlike at first order, the second-order solutions are expected to display nonlinear effects arising from the disorder as the first-order displacement fields are coupled in the source terms in Eq. (31). We discuss such effects in detail in Sec. IX.

D. Higher orders

The higher-order terms in this expansion can now be analyzed in a similar manner. The same recursive scheme can be applied at higher orders, with the sources involving the solutions to the displacement fields at lower orders. For example, the equations of force balance at third order can be written in terms of the solutions at first and second order. Interestingly, due to the recursive structure of our perturbation expansion, the Green's function that appears at all orders are exactly the same. The source terms at higher orders couple the lower-order solutions and hence display nonlinear behavior.

V. POLYDISPERSED SOFT DISKS

In this section, we apply our perturbation expansion to a physically relevant system: soft disks with small polydispersity in particle sizes. We begin with a triangular crystal composed of deformable disks interacting via one sided pairwise potentials that is now paradigmatic in the study of soft particles and deformable foams [11,54]. The form of the potential is

$$V_{\sigma_{ij}}(\vec{r}_{ij}) = \frac{K}{\alpha} \left(1 - \frac{|\vec{r}_{ij}|}{\sigma_{ij}} \right)^{\alpha} \text{ for } r_{ij} < \sigma_{ij},$$

= 0 for $r_{ij} > \sigma_{ij}.$ (37)

Here $\vec{r}_{ij} = \vec{r}_j - \vec{r}_i$ is the vector distance between the particles *i* and *j* located at positions \vec{r}_i and \vec{r}_j , respectively. $\sigma_{ij} = \sigma_i + \sigma_j$ is the sum of the radii σ_i and σ_j of the two particles. Here *K* represents an overall stiffness constant, in the subsequent discussions we set K = 1 for simplicity. The interparticle forces are then given by

$$\vec{f}_{ij} = \frac{K}{\sigma_{ij}} \left(1 - \frac{|\vec{r}_{ij}|}{\sigma_{ij}} \right)^{\alpha - 1} \hat{r}_{ij}, \tag{38}$$

where \hat{r}_{ij} is the unit vector along the \vec{r}_{ij} direction. In this work we present results for the harmonic potential, setting $\alpha = 2$. Our results can easily be generalized to other forms of the interparticle potential. When all the radii are equal, the minimum energy configuration of the system is the crystalline state with the particles forming a triangular lattice. Choosing all the radii σ_i to be equal to σ_0 , the magnitude of the contact force in the crystalline state f_0 depends on the packing fraction $\phi = \frac{1}{V} \sum_i \pi \sigma_i^2$, and is given by $f_0 = \frac{1}{2\sigma_0} (1 - \sqrt{\phi_c/\phi})$. Here ϕ_c is the packing fraction of the marginal crystal with no overlaps between particles, and therefore no interparticle forces. This occurs in the hexagonally close packed structure, with $\phi_c = \pi/\sqrt{12} \approx 0.9069$. It is also convenient to define a parameter ϵ , that quantifies the overcompression of the system

$$\epsilon = 1 - R_0 = 1 - \sqrt{\frac{\phi_c}{\phi}}.$$
(39)

The quantity ϵ therefore defines the length scale of overlap between particles in the pure crystalline arrangement. Next, a perturbation away from the crystalline state can be caused by a change in the radii at each site

$$\sigma_i = \sigma_0 + \lambda \delta \sigma_i. \tag{40}$$

Therefore, we can identify the radii of the particles as the quenched random variables that appear in the perturbation expansion in Sec. III. We have

$$\zeta \equiv \sigma. \tag{41}$$

The displacement fields in this system can then be derived using the techniques presented in Sec. III, For the harmonic PHYSICAL REVIEW E **104**, 034608 (2021)

case ($\alpha = 2$) the coefficients $C_{ij}^{\alpha\beta}$ that appear in the Green's function have particularly simple forms, and are given in the Appendix. The Green's functions for this system in Fourier space are given by

$$\widetilde{G}^{xx}(\vec{k}) = \Gamma_1 \frac{(1-\epsilon)}{\Gamma_1 \Gamma_2 - \Gamma_3^2},
\widetilde{G}^{xy}(\vec{k}) = \Gamma_3 \frac{(1-\epsilon)}{\Gamma_1 \Gamma_2 - \Gamma_3^2},
\widetilde{G}^{yx}(\vec{k}) = \Gamma_3 \frac{(1-\epsilon)}{\Gamma_1 \Gamma_2 - \Gamma_3^2},
\widetilde{G}^{yy}(\vec{k}) = \Gamma_2 \frac{(1-\epsilon)}{\Gamma_1 \Gamma_2 - \Gamma_3^2},$$
(42)

where the functions Γ_1 , Γ_2 , Γ_3 have the following forms:

$$\Gamma_1 = (3 - 4\epsilon)\cos(k_x)\cos(k_y) - 2\epsilon\cos(2k_x) + 6\epsilon - 3,$$

$$\Gamma_2 = (1 - 4\epsilon)\cos(k_x)\cos(k_y) + 2(1 - \epsilon)\cos(2k_x) + 6\epsilon - 3,$$

$$\Gamma_3 = \sqrt{3}\sin(k_x)\sin(k_y).$$
(43)

VI. SINGLE DEFECT: SERIES SOLUTION FOR DISPLACEMENT FIELDS

In this section, we use the perturbation theory developed in Secs. III and IV to compute the displacement fields generated by the presence of a single defect in the crystalline background. To model such a situation, we increase the radius of a single particle by an amount $\delta\sigma$ at a position \vec{R} in the crystalline arrangement. This causes an excess outward displacement $\delta \vec{r} \equiv \{\delta x, \delta y\}$ of each grain as a response to the increase in the radius of the defect particle. Such inhomogeneities in materials are termed stress defects, since the defect causes an outward stress away from it. In the continuum elasticity framework, the stress and displacement are related through a stress geometry equation involving the elastic moduli, which can then be used to solve for a displacement field. In our case of a lattice of finite-sized particles, the displacements give rise to forces through a microscopic force law, which through force-balance conditions leads to a unique solution for the displacement fields. In addition, since we solve the equations of force balance simultaneously, our formulation can also be used to incorporate disorder at the microscopic scale.

In continuum elasticity, the displacement fields $\vec{u} \equiv \delta \vec{r}$ arising due to localised excess forces can be obtained using the well-known Lamé equation, which in two dimensions is [6]

$$\mu \nabla^2 \vec{u}(\vec{r}) + (\lambda + \mu) \vec{\nabla} [\vec{\nabla} \cdot \vec{u}(\vec{r})] = -\vec{f}(\vec{r}), \qquad (44)$$

where μ and λ are the Lamé coefficients derived from the elastic moduli of the solid. The field $\vec{f}(\vec{r})$ represents the body force acting on the system at position \vec{r} . Using the known elastic moduli for the triangular geometry, one can therefore obtain the displacement fields in the presence of external forces using Eq. (44). The generalization of this procedure to the case of a single stress defect can be obtained by solving the homogeneous case of Eq. (44) in a cylindrical geometry with a uniform normal force applied at the inner boundary. However,



FIG. 3. The displacements of each grain away from their crystalline positions, produced by a single defect. Here each point in the *xy* plane represents the original crystalline position of the grain. (a) The displacement of each grain along the *x* direction obtained from the simulations. (b) The displacement of each grain along the *x* direction obtained from the perturbation expansion at linear order. (c) The displacement of each grain along the *y* direction obtained from the simulations. (d) The displacement of each grain along the *y* direction obtained from the simulations. (d) The displacement of each grain along the *y* direction obtained from the perturbation expansion at linear order. (e) The displacement fields along the *x* direction $\delta x - \delta x^{(1)}$ with the linear-order solutions subtracted from the displacement fields along the *y* direction $\delta y - \delta y^{(1)}$ with the linear-order solutions subtracted from the displacement form simulations. (h) The displacement of each grain along the *y* direction obtained from the displacement of each grain along the *y* direction obtained from the subtracted from the displacement fields along the *y* direction $\delta y - \delta y^{(1)}$ with the linear-order solutions subtracted from the displacements obtained from simulations. (h) The displacement of each grain along the *y* direction obtained from the perturbation expansion at second order. Note the difference in the magnitudes between the solutions at first and second order.

it as yet unclear how such Lamé equations emerge from a microscopic treatment of the finite-size of the particles, which can cause sensitive corrections to the continuum predictions. Our exact framework therefore provides an interesting route to verify the isotropic elasticity of a medium composed of finite-sized units. We show that the case of a triangular lattice arrangement yields displacement fields which display the underlying lattice symmetries at short length scales. However, in Sec. VIII we show that the exact displacement fields at large distances away from a single defect obey the above continuum equations. The linear displacement fields along with Eq. (44) enables us to derive the macroscopic elastic moduli in terms of the coefficients obtained from the underlying interpaticle potential. The higher-order solutions in our expansion can therefore be used to predict nonlinear corrections to continuum elasticity that arise in athermal systems.

A. Linear order

We begin by placing a single defect particle with a larger radius $\sigma_0 + \delta \sigma$ at the origin. The quenched disorder field is therefore nonzero only at the single site and is given by

$$\sigma(\vec{r}) = \sigma_0 + \delta\sigma\delta(\vec{r}), \tag{45}$$

leading to a constant source field in Fourier space $\delta \tilde{\sigma}(\bar{k}) = \delta \sigma$. We first derive the displacement fields generated by the defect at the origin using the perturbation theory at linear order. It has been shown recently that mechanical equilibrium at linear order leads to nontrivial effects on fluctuations and correlations in athermal near-crystalline systems [22,34]. The field in Eq. (45) can be used as a source in Eq. (29). This yields the displacement fields at linear order { $\delta x^{(1)}, \delta y^{(1)}$ }. We

next compare these with displacement fields obtained from a numerically minimized configuration of a single defect in the crystalline background. In Figs. 3(a) and 3(c) we plot the *x*-displacement fields and *y*-displacement fields obtained from the numerical simulations. We also plot the linear-order displacement fields $\delta x^{(1)}$ and $\delta y^{(1)}$ obtained from the perturbation expansion using Eq. (29) in Figs. 3(b), and 3(d). The displacement fields obtained from our numerical minimization match exactly with the displacement fields computations at linear order. The difference between these two arises in the second-order terms in our perturbation expansion.

B. Second order

We next study the *difference* between the displacements obtained from our numerical minimization using the FIRE [55] algorithm and the predictions of our perturbation theory at linear order. We compute the second-order displacement fields along the x direction $\delta x^{(2)}$ and y direction $\delta y^{(2)}$ using Eq. (36). This involves the displacement fields at first order $\{\delta x^{(1)}, \delta y^{(1)}\}$, which can be used to create the source term at second order using Eq. (31). The coefficients $C_{ii}^{\alpha\beta\gamma}$ that appear in these source terms are given in the Appendix. This yields the displacement fields at second order $\{\delta x^{(2)}, \delta y^{(2)}\}$, using the Green's function formalism in Eq. (36). We next compare these theoretical results at second order, with the difference between the displacement fields obtained from numerical minimization and the theoretically computed linear-order displacements $\{\delta x - \delta x^{(1)}, \delta y - \delta y^{(1)}\}$. These are plotted in Figs. 3(e) and 3(g). The theoretical predictions of the secondorder displacement field is displayed in Figs. 3(f) and 3(h). The displacement fields obtained from numerical minimiza-



FIG. 4. Displacement fields produced by a single defect at third order, obtained by subtracting the first and second-order solutions of the perturbation expansion from the numerically obtained displacements (a) along the *x* direction $\delta x - \delta x^{(1)} - \delta x^{(2)}$ and (b) along the *y* direction $\delta y - \delta y^{(1)} - \delta y^{(2)}$. These displacement fields resemble the first and second-order solutions, with a rescaling factor.

tion match with our theoretical predictions at second order exactly. The difference between these two arises in the thirdorder terms in our perturbation expansion. Remarkably, these second-order displacement fields are very similar to the displacement fields obtained at first order, with a scaling factor $\mathcal{O}(\delta\sigma)$. We discuss the origin of such behavior in our perturbation expansion in Sec. VIII.

C. Third order

Following our method in Sec. IV C, the equations of force balance at third order can next be written in terms of the solutions at lower orders. Once again, we can obtain these solutions, using the Green's function formalism, with the sources at third order involving the displacement fields at first and second order. This procedure is straightforward, and we have not attempted to extract the displacement fields at third order theoretically. Instead, we have numerically extracted the displacement fields at third order by subtracting the theoretically obtained lower order solutions $\delta x(y)^{(1)}$ and $\delta x(y)^{(2)}$ from the actual displacements $\delta x(y)$ obtained in the numerically minimized configuration with a single defect. The quantities $\delta x - \delta x^{(1)} - \delta x^{(2)}$ and $\delta y - \delta y^{(1)} - \delta y^{(2)}$, which represent the third-order solutions, are plotted in Figs. 4(a) and 4(b), respectively. Once again, we find that the third-order displacement fields produced by a single defect in our perturbation expansion display very similar behavior to the first-order displacement fields, with a scaling factor $\mathcal{O}(\delta\sigma^2)$.

VII. FORCES PRODUCED BY A DEFECT

We next analyze the change in interparticle forces caused by the presence of a single defect in the system. Since the force at each bond depends on the displacements of the corresponding particles, we can use the displacement fields as predicted from our theory to calculate the interparticle forces at all orders. The change in interparticle forces between particles i and j can be computed at linear order from the expressions in Eq. (20). We have

$$\delta f_{ij}^{x(1)} = \frac{1}{V} \sum_{\vec{k}} \left\{ \left[C_{ij}^{xx} \delta \tilde{x}^{(1)}(\vec{k}) + C_{ij}^{xy} \delta \tilde{y}^{(1)}(\vec{k}) \right] \left[1 - \mathcal{F}_j(\vec{k}) \right] \right\} \\ + C_{ij}^{x\sigma} \left[1 + \mathcal{F}_j(\vec{k}) \right] \delta \tilde{\sigma}(\vec{k}) \right\} \exp(-i\vec{k}.\vec{r}_i),$$



FIG. 5. The components of the interparticle forces parallel to the original lattice directions f_{\parallel} and perpendicular to the lattice directions f_{\perp} . (a) Plot of $\ln(|\delta f_{\parallel}|)$ at each bond produced by a single defect plotted at their original crystalline positions obtained from simulations. (b) $\ln(|\delta f_{\parallel}|)$ at each bond produced by a single defect obtained from the perturbation expansion at linear order. (c) $\ln(|\delta f_{\perp}|)$ at each bond produced by a single defect obtained from simulations. (d) $\ln(|\delta f_{\perp}|)$ at each bond produced by a single defect obtained from simulations. (d) $\ln(|\delta f_{\perp}|)$ at each bond produced by a single defect obtained from simulations.

$$\delta f_{ij}^{y(1)} = \frac{1}{V} \sum_{\vec{k}} \left\{ \left[C_{ij}^{yx} \delta \tilde{x}^{(1)}(\vec{k}) + C_{ij}^{yy} \delta \tilde{y}^{(1)}(\vec{k}) \right] [1 - \mathcal{F}_j(\vec{k})] + C_{ij}^{y\sigma} [1 + \mathcal{F}_j(\vec{k})] \delta \tilde{\sigma}(\vec{k}) \right\} \exp(-i\vec{k}.\vec{r}_i).$$
(46)

To better elucidate the nature of the forces in this athermal crystalline system, we define the parallel and perpendicular components of the interparticle forces with respect to the *original* lattice directions \hat{r}_{\parallel} and \hat{r}_{\perp} as f_{\parallel} and f_{\perp} (see Fig. 1). The deviation of these forces from their crystalline values δf_{\parallel} and δf_{\perp} can be thus be expressed as

$$\delta f_{\parallel} = |f_{ij}| \cos\left(\theta_{ij} - \theta_{ij}^{0}\right) - f_{0},$$

$$\delta f_{\perp} = |f_{ij}| \sin\left(\theta_{ij} - \theta_{ij}^{0}\right), \qquad (47)$$

where $|f_{ij}|$ represents the magnitude of the force between particles *i* and *j*, θ_{ij} is the bond angle between *i* and *j*, and $\theta_{ii}^{(0)}$ is its value in the crystalline ordered state. Using this decomposition we find that although both $|\delta f_x|$ and $|\delta f_y|$ have magnitudes of the same order, surprisingly the δf_{\perp} caused by a single defect is much smaller in magnitude in comparison to δf_{\parallel} . To display this difference, in Figs. 5(a) and 5(c) we plot $\ln(|\delta f_{\parallel}|)$ and $\ln(|\delta f_{\perp}|)$, respectively, at each bond produced by a single defect from our simulations, while in Figs. 5(b) and 5(d) we plot $\ln(|\delta f_{\parallel}|)$ and $\ln(|\delta f_{\perp}|)$, respectively, from the theoretically computed interparticle forces. This difference in the magnitude of the parallel and orthogonal components of forces produced by a single defect is the origin of constrained fluctuations in the orthogonal components of forces in minimally polydispersed disordered crystals [22]. As superposition holds at linear order, the fluctuations in δf_{\perp} produced by multiple defects, are also restricted. It should be noted that this effect only emerges by exactly solving *all* the equations of force balance simultaneously.

VIII. LARGE DISTANCE ASYMPTOTICS

In this section, we analyze the large distance behavior of the solutions to the displacement fields. We focus on the linear-order solutions and derive the continuum behavior of the displacement field produced by a single defect in the system. To obtain the large distance behavior as $r \to \infty$, we analyze the solutions of the displacement fields in the small $k \to 0$ limit. It is convenient to work in radial coordinates in Fourier space $[\vec{k} = (k, \psi)]$. The Green's functions of the response given in Eq. (42) can be simplified in the small k limit $(k \to 0)$ to yield

$$\tilde{G}^{xx}(k,\psi,\epsilon) = -\frac{2(\epsilon-1)(4\epsilon\cos(2\psi)+8\epsilon-3)}{k^2(16\epsilon^2-16\epsilon+3)(\cos(2\psi)+2)^2},$$

$$\tilde{G}^{xy}(k,\psi,\epsilon) = -\frac{2\sqrt{3}(\epsilon-1)\sin(2\psi)}{k^2(16\epsilon^2-16\epsilon+3)(\cos(2\psi)+2)^2},$$

$$\tilde{G}^{yy}(k,\psi,\epsilon) = -\frac{2(\epsilon-1)(4(\epsilon-1)\cos(2\psi)+8\epsilon-5)}{k^2(16\epsilon^2-16\epsilon+3)(\cos(2\psi)+2)^2},$$
(48)

with $\tilde{G}^{yx} = \tilde{G}^{xy}$. These Green's functions in Fourier space have the form $\tilde{G}^{\mu\nu} = \frac{\tilde{g}^{\mu\nu}(\psi,\epsilon)}{k^2}$. The prefactor $\tilde{g}^{\mu\nu}(\psi,\epsilon)$ depends on the overcompression ϵ and hence on the packing fraction ϕ . This asymptotic behavior in Fourier space leads to a prediction of $G^{\mu\nu}(\vec{r}) \sim \log(|r|)$ for large distances r for all the Green's functions in real space. These Green's functions in real space have been plotted in Fig. 2.

Next, the linear-order source terms can be extracted from the functions D^x and D^y given in Eq. (25), which in the small *k* limit can be simplified as

$$D^{x}(k, \psi, \epsilon) = i6(1 - 2\epsilon)k\cos\psi,$$

$$D^{y}(k, \psi, \epsilon) = i2\sqrt{3}(1 - 2\epsilon)k\sin\psi.$$
(49)

Finally, using the expressions in Eqs. (48) and (49) we arrive at the first-order displacement fields in Fourier space in the small *k* limit. We have

$$\delta \tilde{x}^{(1)}(k,\psi,\epsilon) = i\delta\sigma \frac{12}{k} \frac{(1-\epsilon)(1-2\epsilon)}{3-4\epsilon} \frac{\cos(\psi)}{2+\cos(2\psi)},$$

$$\delta \tilde{y}^{(1)}(k,\psi,\epsilon) = i\delta\sigma \frac{4\sqrt{3}}{k} \frac{(1-\epsilon)(1-2\epsilon)}{3-4\epsilon} \frac{\sin(\psi)}{2+\cos(2\psi)}.$$

(50)

We next consider the large distance behavior in the continuum limit, where $r/R_0 \rightarrow \infty$, as well as $N \rightarrow \infty$. The displacement fields at large distances *r* away from the defect can then be expressed as

$$\delta x^{(1)}(r,\theta) = \frac{2}{4\pi^2} \int_{-\pi}^{\pi} d\psi \int_0^{\infty} \delta \tilde{x}^{(1)}(k,\psi) \exp(-i\vec{k}.\vec{r})kdk,$$

$$\delta y^{(1)}(r,\theta) = \frac{2}{4\pi^2} \int_{-\pi}^{\pi} d\psi \int_0^{\infty} \delta \tilde{y}^{(1)}(k,\psi) \exp(-i\vec{k}.\vec{r})kdk.$$
(51)



FIG. 6. The displacement fields produced by a single defect for two different sizes of the defect, $\delta\sigma = 0.005$ and $\delta\sigma = 0.01$. The points represent the displacement fields obtained from simulations, and the solid lines represent our theoretical predictions at linear order. (a) The magnitude of the displacements fields $|\delta x|$, at distances measured along the 0° angle with respect to the *x* axis. (Inset) These displacement fields scale linearly with $\delta\sigma$. (b) The magnitude of displacement fields $|\delta y|$, at distances measured along the 60° angle with respect to the *x*-axis. (Inset) These displacement fields scale linearly with $\delta\sigma$. The dashed lines represent our asymptotic predictions at large distances, given in Eq. (52). The prefactor is given by $C = \frac{2\sqrt{3}\delta\sigma(1-\epsilon)(1-2\epsilon)}{\pi(3-4\epsilon)}$. Here we choose $\phi = 0.92$ which sets $\epsilon = 7.14 \times 10^{-3}$ using Eq. (39).

The factors of 2 that appear in the above expressions, represent the equal contributions to the integral from the singular behavior of the Green's functions in Eq. (42) at the points (0,0) and (π, π) . Finally, evaluating the above integrals using the expressions in Eq. (50), we arrive at the following asymptotic forms of the linear-order displacement fields at large distances:

$$\delta x^{(1)}(r,\theta) = C \delta \sigma \frac{\cos \theta}{r},$$

$$\delta y^{(1)}(r,\theta) = C \delta \sigma \frac{\sin \theta}{r},$$
 (52)

where the prefactor C depends on the overcompression ϵ and can be computed exactly. We have

$$C = \frac{2\sqrt{3}(1-\epsilon)(1-2\epsilon)}{\pi(3-4\epsilon)}.$$
(53)

We therefore find that in the continuum limit, the displacement fields at first order $\delta \vec{r}^{(1)}$ decay isotropically outwards from the defect as $\sim \frac{1}{r}$ at large distances. We note that the continuum limit solutions in Eq. (52) satisfy the Lamé equations in Eq. (44). From the self similarity of the higher-order solutions at large distances, we expect the continuum limits of the displacement fields at higher orders to also satisfy Eq. (44). This leads to corrections to the Lamé coefficients and consequently corrections to the elastic moduli that arise from the higher orders in our perturbation expansion, which in turn arise from the higher derivatives of the underlying interparticle potential. In Figs. 6(a) and 6(b) we plot the magnitude of the x component of the displacement field along $\theta = 0^0$ and the y-component of the displacement field along $\theta = 60^{\circ}$, with increasing distance away from the defect. We plot these displacement fields for two different sizes of the defect $\delta \sigma =$ 0.005 and $\delta \sigma = 0.01$. We also plot their scaling behavior with $\delta\sigma$ along different angles θ in the insets of Figs. 6(a) and 6(b), which are in agreement with our predictions in Eq. (52). We also display the convergence of these results to our continuum predictions in Eq. (52).

We note that our formalism can easily be generalized to three dimensions, with the Green's functions once again displaying a $1/k^2$ dependence as in the case of a two-dimensional system. However, Eq. (51) changes as an integration over a three dimensional reciprocal space is required. This leads to a $1/r^2$ scaling of the displacement fields for large values of r. For a general d dimensional system, a $1/r^{d-1}$ behavior is obtained.

Next, the asymptotic behavior of the excess forces can also be computed from the displacement field at large distance. Considering the forces between neighboring particles *i* and *j* located at a large distance away from the defect, we have $r_i \simeq r_j \simeq r$ and $\theta_i \simeq \theta_j \simeq \theta$. Here $r_i = |\vec{r}_i|$ is the distance of the particle from the defect, and θ_i is the angle of the distance vector \vec{r}_i with respect to the *x*-axis. Using Eq. (52), the relative displacements at linear order can be expressed as

$$\delta x_{ij}^{(1)} = \delta x_j - \delta x_i = \vec{\mathbb{r}}_j \cdot \vec{\nabla} \delta x(\vec{r}),$$

$$\delta y_{ij}^{(1)} = \delta y_j - \delta y_i = \vec{\mathbb{r}}_j \cdot \vec{\nabla} \delta y(\vec{r}),$$
 (54)

where \vec{r}_j are the fundamental translation vectors of the lattice with $\vec{r}_j = R_0(\cos\theta_{ij}^0\hat{x} + \sin\theta_{ij}^0\hat{y})$ and $\theta_{ij} = \theta_j - \theta_i$. Using the expressions for the large distance behavior of the displacement fields in Eq. (52), the relative displacements at linear order can be simplified to the following form

$$\delta x_{ij}^{(1)}(r,\theta) = -\delta \sigma \frac{R_0 \mathcal{C}}{r^2} \cos\left(2\theta - \theta_{ij}^0\right),$$

$$\delta y_{ij}^{(1)}(r,\theta) = -\delta \sigma \frac{R_0 \mathcal{C}}{r^2} \sin\left(2\theta - \theta_{ij}^0\right).$$
(55)

We can next use these to compute the asymptotic behavior of the change in interparticle forces produced by a single defect at linear order. Using the expressions in Eq. (55) in Eq. (18), we arrive at the excess forces at large distances away from the defect,

$$\delta f_{ij}^{x(1)}(r,\theta) = \mathcal{B}_{j}^{x}(\theta) \frac{\delta\sigma}{r^{2}},$$

$$\delta f_{ij}^{y(1)}(r,\theta) = \mathcal{B}_{j}^{y}(\theta) \frac{\delta\sigma}{r^{2}},$$
 (56)

where the constants are given by

$$\mathcal{B}_{j}^{x}(\theta) = -R_{0}\mathcal{C}\left[C_{ij}^{xx}\cos\left(2\theta - \theta_{ij}^{0}\right) + C_{ij}^{xy}\sin\left(2\theta - \theta_{ij}^{0}\right)\right],$$

$$\mathcal{B}_{j}^{y}(\theta) = -R_{0}\mathcal{C}\left[C_{ij}^{yx}\cos\left(2\theta - \theta_{ij}^{0}\right) + C_{ij}^{yy}\cos\left(2\theta - \theta_{ij}^{0}\right)\right].$$

(57)

In Fig. 7(a), we plot the $|\delta f_x|$ along an angle $\theta = 0^0$ with respect to x axis for two different defect sizes $\delta \sigma = 0.005$ and $\delta \sigma = 0.01$. Our simulation results match with our predictions from the linear theory exactly, and display a $|\delta f^x| \sim 1/r^2$ behavior at large distances r away from the defect. In Fig. 7(b), we plot the $|\delta f_y|$ field at an angle $\theta = 60^\circ$ with respect to the x axis. Once again these display a $|\delta f^y| \sim 1/r^2$ behavior at large distances r from the defect. We also plot the scaling behavior of these excess forces with $\delta \sigma$ along different angles θ in the



FIG. 7. The excess force at each bond produced by a single defect for two different sizes of the defect, $\delta \sigma = 0.005$ and $\delta \sigma = 0.01$. The points represent forces obtained from simulations, and the solid lines represent our theoretical predictions at linear order. (a) The magnitude of the excess force $|\delta f_x|$ at each bond, for distances measured along the 0° angle with respect to the *x*-axis. (Inset) These excess force fields scale linearly with $\delta \sigma$. The plots display the excess forces for the bond along j = 0. (b) The magnitude of the excess force $|\delta f_y|$ at each bond, for distances measured along the 0° angle with respect to the *x*-axis. (Inset) These excess force to the *x*-axis. (Inset) These excess force fields scale linearly with $\delta \sigma$. The dashed lines represent our asymptotic predictions at large distances, given in Eq. (56). The plots display the excess forces for the bond along j = 1.

insets of Figs. 7(a) and 7(b), which are in agreement with our theoretical predictions. We also display the convergence of these results to our continuum predictions in Eq. (56). The finite perpendicular components of the interparticle forces produced by a single defect in the system can be attributed to the finite size of the lattice which appears through the vectors \vec{r}_j in Eq. (54). It is interesting to note that such an effect does not arise in continuum elasticity, as the solutions in Eq. (52) predict purely radial forces away from the defect in the continuum limit.

A. Universal behavior

Many of our results derived for the system of polydispersed soft disks are universal, with the microscopic details of the model only changing the coefficients in the perturbation expansion developed in Sec. III. However, the underlying symmetries of the crystalline background persist in these coefficients, which could lead to differing behavior at short length scales. While at small distances, the nature of the underlying lattice and the details of the force law are important, the large distance behavior displays universal properties. As we have shown in Sec. VIII, our displacement fields at linear order do not display the hallmarks of the underlying lattice at large length scales, displaying isotropic behavior which also agrees with the predictions of continuum elasticity. However, as evidenced by the discussion of the higher-order coefficients $C_{ii}^{\alpha\beta\gamma}$ in Sec. III, these symmetries could play an important role in the corrections to universal behavior. The Green's function $G^{\mu\nu}(\vec{r})$ arising in our perturbation expansion can be derived for any central potential in a similar manner as in Sec. V. Additionally, since the solutions to the displacement fields at all orders involve the same Green's function, we can use the properties of the higher-order sources to determine the universal scaling behavior at higher orders. Since the displacement

fields produced by a single defect decay with distance, these can be considered to be localized when the large length-scale behavior is considered. Therefore, the source terms at higher orders arising from a single defect are also localized. This naturally leads to an explanation for the self similarity at all orders of the displacement fields arising from a single defect at large length scales.

The second-order and higher-order displacement fields produced by a single defect in the crystalline background also arise from localized sources, and are therefore expected to decay as 1/r at large distances with "effective charges" that control the magnitude at each order. Additionally, we expect these higher-order displacement fields to be universal for all central potentials, with the displacement fields decaying as 1/r away from a defect, with the prefactors dependent on the underlying force law. Such behavior can in turn be described by effective continuum equations at the coarse grained scale, which involve renormalized coefficients that include the higher terms in our perturbation theory. Although rotational invariance emerges at the large length scales away from a single defect in our theory, the higher-order interactions between them encode the crystalline symmetries of the initial state, which we expect to persist in the large distance behavior. This is in contrast to fully amorphous structures, where the lack of a reference state precludes the identification of such symmetries. We therefore expect rotational symmetries to emerge at large length scales in such systems as the microscopic disorder is increased. It would therefore be interesting to understand how our perturbation expansion breaks down as the disordered amorphous state is approached with larger amounts of disorder in the system.

IX. NONLINEAR CORRECTIONS ARISING FROM TWO DEFECTS

Finally, we provide interesting avenues to test nonlinear corrections to continuum elasticity in near-crystalline athermal systems. Having studied the displacement fields generated by a single defect in the crystalline background within our perturbation expansion, we turn to a nontrivial application of our theory, the case of two defects in a crystalline background. The second-order corrections to the displacement fields produced by a single defect displayed in Fig. 3 can be obtained by subtracting the linear-order solution from the numerically minimized displacement fields, as described in Sec. VII. Therefore, such a quantity is not directly accessible through numerical simulations or experiments. We show below that such nonlinear corrections can naturally be tested through numerically generated energy-minimized configurations with two defects. The case of two defects therefore serves as an illustrative example of the nontrivial exact predictions of our theory.

The displacement fields generated by a single defect placed at positions $\vec{0}$ and $\vec{\Delta}$, respectively, can be expressed in terms of our perturbation expansion as

$$\delta \vec{r}_{\vec{0}} = \delta \vec{r}_{\vec{0}}^{(1)} + \delta \vec{r}_{\vec{0}}^{(2)} + \delta \vec{r}_{\vec{0}}^{(3)} + \dots,$$

$$\delta \vec{r}_{\vec{\Delta}} = \delta \vec{r}_{\vec{\Delta}}^{(1)} + \delta \vec{r}_{\vec{\Delta}}^{(2)} + \delta \vec{r}_{\vec{\Delta}}^{(3)} + \dots$$
(58)

The left-hand side of the above equation represents the actual displacement fields that can be generated by an exact minimization of the energy. The right-hand side represents the series solution that can be extracted theoretically at each order.

Next, the displacement field arising from two defects placed together in the system at positions $(\vec{0})$ and $(\vec{\Delta})$ can be written in terms of our perturbation expansion as

$$\delta \vec{r}_{\vec{0},\vec{\Delta}} = \delta \vec{r}_{\vec{0},\vec{\Delta}}^{(1)} + \delta \vec{r}_{\vec{0},\vec{\Delta}}^{(2)} + \delta \vec{r}_{\vec{0},\vec{\Delta}}^{(3)} + \dots$$
(59)

As is apparent from the Green's function formalism in Eq. (29), the displacement field arising from multiple defects at first order can be computed as a superposition of the displacement fields arising from each defect individually. Therefore,

$$\delta \vec{r}_{\vec{0},\vec{\Delta}}^{(1)} = \delta \vec{r}_{\vec{0}}^{(1)} + \delta \vec{r}_{\vec{\Delta}}^{(1)}.$$
 (60)

The second-order displacement fields arising from the two defects cannot be computed as the superposition of the displacement fields arising from each of them and therefore the second-order fields for two defects cannot be described by the two individual fields alone. This nonlinearity is encoded in the source terms at second order derived in Eq. (31) which involves a nonlinear coupling of the linear-order displacement fields. Therefore, the second-order displacement fields arising from two defects together do not obey superposition. A nontrivial correction at second order can therefore be extracted from the combination

$$\delta \vec{r}_{\vec{0},\vec{\Delta}} - \delta \vec{r}_{\vec{0}} - \delta \vec{r}_{\vec{\Delta}} = \delta \vec{r}_{\vec{0},\vec{\Delta}}^{(2)} - \delta \vec{r}_{\vec{0}}^{(2)} - \delta \vec{r}_{\vec{\Delta}}^{(2)}.$$
 (61)

Once again, the left-hand side and right-hand side of the above equation represent quantities that can be extracted numerically from energy-minimized configurations and from our perturbation theory, respectively. We note that the quantity in Eq. (61) arises purely at second order in our perturbation expansion.



FIG. 8. Plot of the interaction in displacement fields due to two defects in the crystalline background $\delta \vec{r}_{0,\vec{\Delta}} - \delta \vec{r}_{0} - \delta \vec{r}_{\vec{\Delta}}$. Here the field $\delta \vec{r}_{0,\vec{\Delta}}$ represents the displacements obtained by placing two defects at (0,0) and (Δ , 0) together, while $\delta \vec{r}_{0}$ and $\delta \vec{r}_{\vec{\Delta}}$ are the individual displacement fields generated by placing single defects at $\vec{r}_{0} = (0, 0)$ and $\vec{r}_{\vec{\Delta}} = (\Delta, 0)$, respectively. The magnitude of this interaction is small, which is due to the second-order nature of this quantity. This naturally arises within our perturbation expansion, and matches with the numerically generated fields exactly. Here the system size is N = 50, and the defects are placed a distance $\Delta = 20$ apart along the *x* direction. These configurations have been shifted using periodic boundary conditions to aid visualization. In our simulations in panel (a), we ensure that $|\sum_{j} \vec{f}_{ij}| \leq 10^{-11}$ for each particle *i*, which is necessary to extract the sensitive corrections presented in panel (b).

Such a prediction can be tested experimentally in systems where strains and forces can be measured, such as in photoelastic disks. We expect the effect become more prominent as one increases the size of the defect particles, with the intensity of the effect scaling as $\delta\sigma^2$.

In Fig. 8 we plot the expression in Eq. (61) obtained from an exact numerical minimization of the system using the FIRE [55] algorithm. We also plot the theoretical quantity in the right-hand side of Eq. (61) obtained from solving the displacement fields up to second order derived in Eqs. (28) and (35). This nontrivial interaction field obtained from simulations matches exactly with our theoretical predictions. We note that the interaction field in Eq. (61) predicted by our perturbation expansion cannot be captured within a continuum elasticity framework, as the corresponding Lamé equations in Eq. (44) are linear. Therefore, such quantities can be used to experimentally test for deviations from linear elasticity in such athermal materials.

X. SUMMARY AND CONCLUSION

We have presented a new theoretical technique to exactly extract the displacement fields in disordered athermal systems near the crystalline state. Our hierarchical perturbation expansion about the crystalline state allows us to simultaneously solve the equations of force balance and obtain the displacement fields as a series expansion to arbitrary accuracy. We used this theory to study a physically relevant system of polydispersed soft disks, with disorder introduced in the radii of the particles. We illustrated our technique by exactly computing the displacement fields produced by a single defect introduced into the crystalline background, up to second order. These solutions match exactly with displacement fields extracted from our simulation of the energy-minimized configuration with a single defect. Additionally, we illustrated the remarkable self-similar structure of these solutions at every order. Using our exact results, we derived a $|\delta r| \sim 1/r$ and $|\delta f| \sim 1/r^2$ decay for the displacement fields and excess forces at large distances r away from the defect. Finally, we provided an experimentally testable prediction of our theory, the nonlinear interaction between two defects, that can be extracted purely from the observed displacement fields produced by defects.

The perturbation expansion developed in this paper can easily be extended to involve systems with other types of microscopic disorder, such as spring networks with bond disorder, and also soft particle systems with external pinning forces [34]. Our framework is quite general, and can also be applied to any precompressed crystalline system with particles interacting through central potentials. The techniques developed in this paper can be generalized to study other two and three dimensional systems as well as quasi-onedimensional systems [56]. Our formalism can also be used to study metamaterials which can be created with different periodic backgrounds [57,58]. It would also be interesting to generalize our techniques to systems with friction by incorporating a tunable roughness on the surface of the particles [59,60]. In general, solving the force-balance equations involves the inversion of a large disordered matrix, which has up to now been difficult to formulate in terms of a coarse grained

theory involving the properties of the underlying particles. In this regard our exact expansion techniques represent a useful analytic tool with which to develop coarse-grained theories for such materials.

Since the equations governing continuum elasticity are linear, disordered athermal materials which display detectable nonlinear effects, provide an interesting arena to search for higher-order corrections to linear elasticity. Incorporating microscopic disorder along with force balance at the local level in disordered athermal materials continues to be a theoretical challenge. This is made possible in the paradigm of crystals, which allows an elegant representation of these microscopic degrees of freedom in Fourier space. Since macroscopic constitutive equations are not well-defined for disordered amorphous solids, the formalism introduced in this paper that allows for exact predictions in the presence of microscopic disorder can be useful in understanding the emergence of constitutive equations at large length scales [27].

Since Green's function techniques find applications across various fields of physics, and are the building blocks of more complex emergent theories in continuum, it will be interesting to use our framework to develop nonlinear elasticity theories describing athermal materials [61]. It would also be interesting to develop re-summation techniques to simplify the higher-order terms that appear in these expansions. Finally, our formulation can also be extended to incorporate disorder in the entire system, at linear order [22,34], as well as higher orders, to understand the emergence of amorphous properties in athermal systems with increasing disorder.

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APPENDIX: EXPANSION COEFFICIENTS FOR POLYDISPERSED DISKS

The linear-order coefficients in the perturbation expansion for polydispersed disks can be expressed as (setting K = 1)

$$\begin{split} C_{ij}^{xx}(R_0) &= -\frac{R_0 - \sigma_0 + \sigma_0 \cos\left(\frac{2\pi j}{3}\right)}{4R_0\sigma_0^2},\\ C_{ij}^{xy}(R_0) &= -\frac{\sin\left(\frac{2\pi j}{3}\right)}{4R_0\sigma_0},\\ C_{ij}^{x\sigma}(R_0) &= \frac{(R_0 - \sigma_0)\cos\left(\frac{\pi j}{3}\right)}{4\sigma_0^3},\\ C_{ij}^{yx}(R_0) &= \frac{\sin\left(\frac{2\pi j}{3}\right)}{4R_0\sigma_0},\\ C_{ij}^{yy}(R_0) &= \frac{\sigma_0 - R_0 + \sigma_0\cos\left(\frac{2\pi j}{3}\right)}{4R_0\sigma_0^2},\\ C_{ij}^{y\sigma}(\phi) &= \frac{(R_0 - \sigma_0)\sin\left(\frac{2\pi j}{3}\right)}{4\sigma_0^3}. \end{split}$$

Since the second-order coefficients in the perturbation expansion require an antisymmetrization over indices, it is convenient to define the index $\overline{j} = \text{mod}(j + 3, 6)$, represent-

ing the neighbor of particle i in the opposite direction to j (see Fig. 1). In this notation, we have

$$\begin{split} C_{ij}^{\text{rxr}}(R_0) &= \frac{R_0 \left[\cos\left(\frac{2\bar{\pi}}{3}\right) - \cos\left(\frac{2\bar{\pi}}{3}\right)\right] + \frac{3}{4} \left[\cos\left(\frac{\pi}{3}\right) - \cos\left(\bar{j}\pi\right) - \cos\left(\frac{\pi}{3}\right) + \cos(j\pi)\right]}{8R_0^2\sigma_0} \\ C_{ij}^{\text{rxr}}(R_0) &= \frac{\sin\left(\frac{\pi}{3}\right) - 3\sin(\pi\bar{j}) - \sin\left(\frac{\pi}{3}\right) + 3\sin(\pi\bar{j})}{16R_0^2\sigma_0}, \\ C_{ij}^{\text{rxr}}(R_0) &= \frac{\cos\left(\frac{\pi}{3}\right) + 3\cos(\pi\bar{j}) + 4R_0\sin\left(\frac{2\pi\bar{j}}{3}\right) - \cos\left(\frac{\pi}{3}\right) - 3\cos(\pi\bar{j}) - 4R_0\sin\left(\frac{2\pi\bar{j}}{3}\right)}{32R_0^2\sigma_0}, \\ C_{ij}^{\text{rxr}}(R_0) &= \frac{4R_0 - 2\sigma_0 + \sigma_0 \left[\cos\left(\frac{2\pi\bar{j}}{3}\right) + \cos\left(\frac{2\pi\bar{j}}{3}\right)\right]}{16R_0\sigma_0^3}, \\ C_{ij}^{\text{rxr}}(\phi) &= \frac{\sin\left(\frac{2\pi\bar{j}}{3}\right) - \sin\left(\frac{2\pi\bar{j}}{3}\right)}{16R_0\sigma_0^2}, \\ C_{ij}^{\text{rxr}}(\phi) &= \frac{\sin\left(\frac{2\pi\bar{j}}{3}\right) - \sin\left(\frac{2\pi\bar{j}}{3}\right)}{16R_0\sigma_0^2}, \\ C_{ij}^{\text{rxr}}(R_0) &= \frac{\sin\left(\frac{\pi\bar{j}}{3}\right) - 3\sin(\pi\bar{j}) + 4R_0\sin\left(\frac{2\pi\bar{j}}{3}\right) - \sin\left(\frac{\pi\bar{j}}{3}\right) + 3\sin(\pi\bar{j}) - 4R_0\sin\left(\frac{2\pi\bar{j}}{3}\right)}{32R_0^2\sigma_0}, \\ C_{ij}^{\text{rxr}}(R_0) &= \frac{\sin\left(\frac{\pi\bar{j}}{3}\right) - 3\cos(\pi\bar{j}) - \cos\left(\frac{\pi\bar{j}}{3}\right) - 3\cos(\pi\bar{j})}{16R_0^2\sigma_0}, \\ C_{ij}^{\text{ryr}}(R_0) &= -\frac{\cos\left(\frac{\pi\bar{j}}{3}\right) + 3\cos(\pi\bar{j}) - \cos\left(\frac{\pi\bar{j}}{3}\right) - 3\cos(\pi\bar{j})}{16R_0^2\sigma_0}, \\ C_{ij}^{\text{ryr}}(R_0) &= -\frac{4R_0 \left[\cos\left(\frac{2\pi\bar{j}}{3}\right) - \cos\left(\frac{\pi\bar{j}}{3}\right)\right] - \left[\sin\left(\frac{\pi\bar{j}}{3}\right) + \sin(\pi\bar{j}) - \sin\left(\frac{\pi\bar{j}}{3}\right) - \sin(\pi\bar{j})\right]}{32R_0^2\sigma_0}, \\ C_{ij}^{\text{ryr}}(R_0) &= -\frac{4R_0 \left[\cos\left(\frac{2\pi\bar{j}}{3}\right) - \cos\left(\frac{2\pi\bar{j}}{3}\right)\right] - \left[\sin\left(\frac{\pi\bar{j}}{3}\right) + \sin(\pi\bar{j}) - \sin\left(\pi\bar{j}\right)\right]}{32R_0^2\sigma_0}, \\ C_{ij}^{\text{ryr}}(R_0) &= -\frac{4R_0 \left[\cos\left(\frac{2\pi\bar{j}}{3}\right) + \sin\left(\frac{2\pi\bar{j}}{3}\right)\right]}{16R_0\sigma_0^2}, \\ C_{ij}^{\text{ryr}}(R_0) &= \frac{-4R_0 \left[\cos\left(\frac{2\pi\bar{j}}{3}\right) + \sin\left(\frac{2\pi\bar{j}}{3}\right)\right]}{16R_0\sigma_0^2}, \\ C_{ij}^{\text{ryr}}(R_0) &= \frac{-4R_0 \left[\cos\left(\frac{2\pi\bar{j}}{3}\right) + \sin\left(\frac{2\pi\bar{j}}{3}\right)\right]}{16R_0\sigma_0^2}, \end{aligned}$$

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